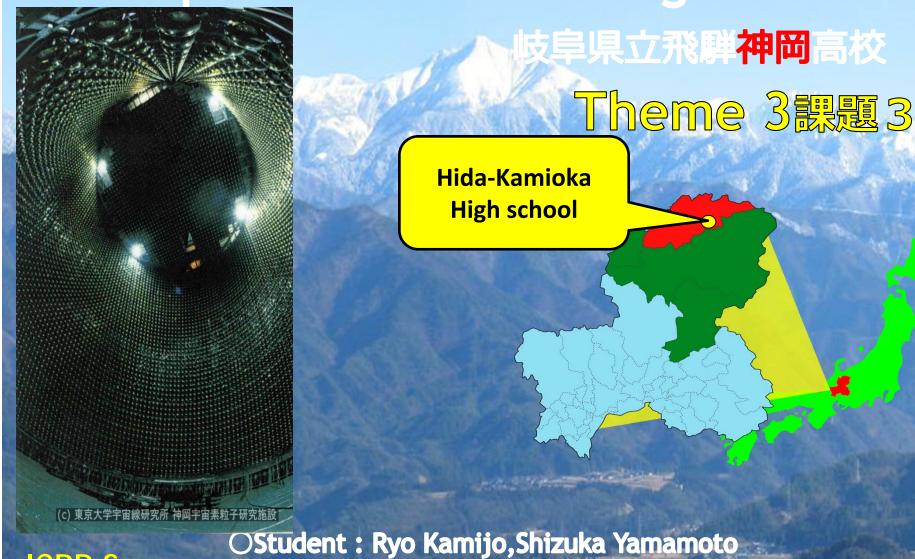
Group8 Hida-Kamioka High School



ICRR Super Kamiokande

Haruki Ushimaru, Ibuki Suzuki, Genki Suzuguchi

Teacher: Hirohiko Taniwaki, Hideki Nakamura

Source

- RT
- ROBOTIS
- UFACTORY
- TOYOTA
- Kawasaki
- THK
- Universal Robots
- ・3次元メディア

- 東京ロボティクス
- Denso
- Kawada
- HITACHI
- Yasukawa
- ABB
- NACHI

social problems of Japan

Ageing population

with declining birthrate



Shortage of labor!

Using robots!!

previous robots = Mainly industrial

Dangerous

Setting costs is expensive

Specialized skills are needed

latest robots = Working Cooperation

1 Safety

2 Setting costs is reasonable

3 Anyone can use

4 Abundant flexibility of usage

1 Safety

Control to avoid injury

- → Touch and stop
- **EX** · Torque control

Current limit (Torque limit) Torque control (Feed back control) real time control.

soft materials

→ rubber

Design

→ smooth shape • People can have familiarity

2 Setting costs is reasonable

Easy construction



3 Anyone can use

Easy program not to use programing language. (EX Tablet operation)



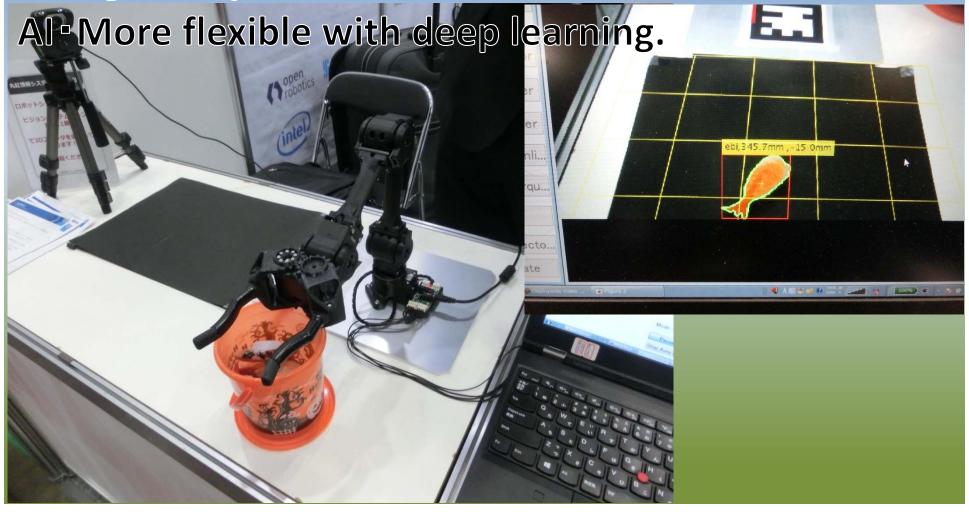
3 Anyone can use

Teaching

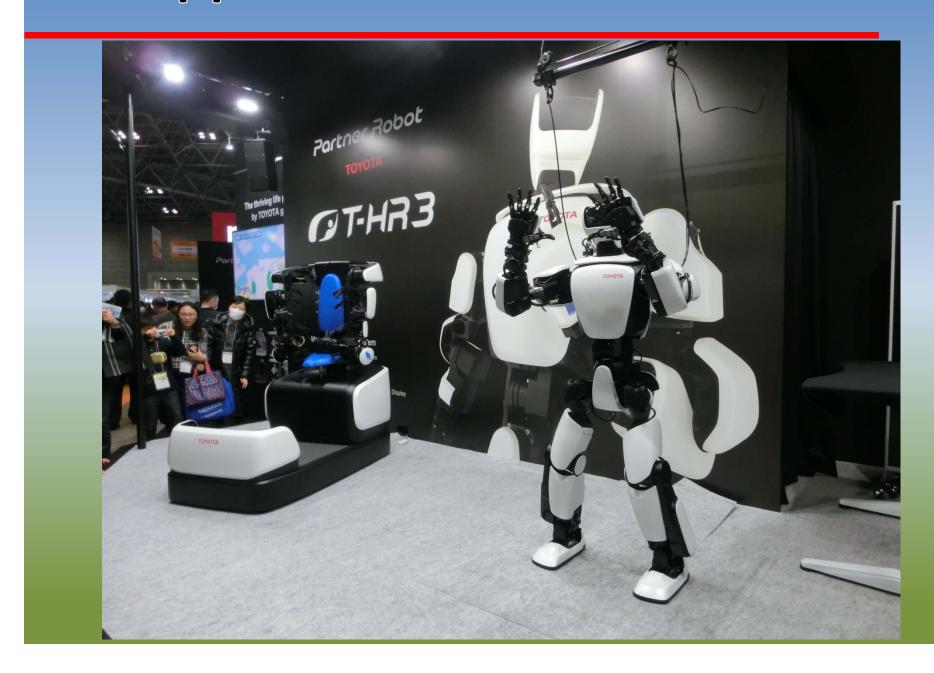


4 Abundant flexibility of usage

Use applications can be changed with software changes only.



The appearance of the future robot



Our robot introduction(^^)/



